Introduction
The FFT/IFFT IP core is a highly configurable Fast Fourier Transform (FFT) and Inverse Fast Fourier Transform (IFFT) VHDL IP component. The core performs an $N$-point complex forward or inverse Discrete Fourier Transform (DFT), where $N$ is any power-of-four value, up to 65,536. The constituent radix-4 processing stages utilize a decimation-in-frequency (DIF) decomposition and internal structure.

The FFT/IFFT core accepts a length $N$ frame of complex data samples, represented as a pair of fixed-point two’s complement numbers. The serial architecture supports throttled loading of data into the core. A ready for processing output indicates the core can accept new data. The serial architecture minimizes resource utilization. The number of bits used to represent input data samples and twiddle factors are independently configurable at build-time. For this architecture, a block floating-point data path representation is used to account for bit growth at the output of each processing stage and to maintain a high degree of precision. The input frame of data samples is presented to the core in natural order. The output frame of data from the core in the transform-domain can be configured for natural or bit-reversed ordering.

The source code for the FFT/IFFT core was developed in a portable, vendor-agnostic manner. The underlying components of the core were developed to infer and take advantage of hardware features found in many FPGAs from various vendors, including Block RAM and hardware multipliers/DSP blocks. The degree of inference of these platform-specific features is controlled via vendor-specific tool settings during the synthesis process.

Additional architectures are also available from GIRD Systems providing other options for transform latency, core throughput, resource utilization, and arithmetic scaling.

Features
- Complex FFT/IFFT operation, run-time configurable on a per-frame basis
- Configurable transform sizes: $N = 4^q$, maximum 65,536; $q = 8$
- Configurable data sample precision
- Configurable twiddle factor precision
- Configurable bit-reversed or natural output ordering
- Fixed-point data interface
- Block floating-point data path for high precision
- Supports serial processing to minimize resource utilization
- Utilizes FPGA architecture features (multiplier/DSP blocks, Block RAM, etc.) via inference
- Bit-accurate MATLAB model and testbench
- VHDL testbench
Interface Description

The component interface is shown in Figure 1.

![FFT/IFFT Core Top-Level Interface](image)

**Generics**

The generic values can be modified at compile time to configure the FFT/IFFT core for the targeted application. Table 1 lists the generics and their purpose.

**Table 1: FFT/IFFT Core Generics**

<table>
<thead>
<tr>
<th>Generic Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>gNUM_STAGES</td>
<td>natural</td>
<td>The number of stages, $q$, needed to generate an $N$ length power-of-four transform in the form $N = 4^q$.</td>
</tr>
<tr>
<td>gDATA_WIDTH</td>
<td>natural</td>
<td>Bit width of input/output data.</td>
</tr>
<tr>
<td>gTWIDDLE_WIDTH</td>
<td>natural</td>
<td>Bit width precision of twiddle factors.</td>
</tr>
<tr>
<td>gORDERING</td>
<td>std_logic</td>
<td>Specifies output data ordering:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>'0': bit-reversed ordering</td>
</tr>
<tr>
<td></td>
<td></td>
<td>'1': natural ordering</td>
</tr>
<tr>
<td>gNUM_MULT_STAGES</td>
<td>natural</td>
<td>Number of pipeline stages used in multiplier operations.</td>
</tr>
</tbody>
</table>

**Inputs**

The signal inputs to the FFT/IFFT core are defined in Table 2.

**Table 2: FFT/IFFT Core Input Signals**

<table>
<thead>
<tr>
<th>Signal Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CLOCK</td>
<td></td>
</tr>
<tr>
<td>RESET_N</td>
<td></td>
</tr>
<tr>
<td>CLEAR</td>
<td></td>
</tr>
<tr>
<td>START</td>
<td></td>
</tr>
<tr>
<td>DATA_I</td>
<td></td>
</tr>
<tr>
<td>DATA_Q</td>
<td></td>
</tr>
<tr>
<td>MODE</td>
<td></td>
</tr>
<tr>
<td>FFT_DATA_I</td>
<td></td>
</tr>
<tr>
<td>FFT_DATA_Q</td>
<td></td>
</tr>
<tr>
<td>BLK_EXP</td>
<td></td>
</tr>
<tr>
<td>READY</td>
<td></td>
</tr>
<tr>
<td>VALID</td>
<td></td>
</tr>
</tbody>
</table>
Input Name | Type | Description
----------|------|-----------------|
CLOCK     | std_logic | Core processing clock.
RESET_N\(^1\) | std_logic | Active low, asynchronous reset.
CLEAR\(^1\) | std_logic | Active high, synchronous reset.
START     | std_logic | Specifies the first sample in an input data frame. \(N-1\) input samples must follow this pulse on consecutive clock cycles.
DATA_I    | signed(gDATA_WIDTH-1:0) | Real (in-phase) input data samples. The bit width is specified by gDATA_WIDTH.
DATA_Q    | signed(gDATA_WIDTH-1:0) | Imaginary (quadrature) input data samples. The bit width is specified by gDATA_WIDTH.
MODE      | std_logic | Specifies the mode of operation: ‘0’: forward FFT ‘1’: inverse FFT This value is accepted when START is asserted.

Outputs
The signal outputs from the FFT/IFFT core are defined in Table 3.

<table>
<thead>
<tr>
<th>Output Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>FFT_DATA_I</td>
<td>signed(gDATA_WIDTH-1:0)</td>
<td>Real (in-phase) output data samples in the transform domain. The bit width is specified by gDATA_WIDTH.</td>
</tr>
<tr>
<td>FFT_DATA_Q</td>
<td>signed(gDATA_WIDTH-1:0)</td>
<td>Imaginary (quadrature) output data samples in the transform domain. The bit width is specified by gDATA_WIDTH.</td>
</tr>
<tr>
<td>BLK_EXP</td>
<td>natural</td>
<td>Indicates the block exponent. The output data from each radix-4 stage can grow by up to 3 bits; BLK_EXP tracks the amount of bit shift scaling that was applied to prevent overflow. For example, a value of 7 indicates samples were shifted right by 7 bits, thus the magnitude of the output is: (FFT_DATA \times 2^{BLK_EXP}).</td>
</tr>
<tr>
<td>READY</td>
<td>std_logic</td>
<td>Indicates the core is ready to accept a new frame of input data.</td>
</tr>
<tr>
<td>VALID</td>
<td>std_logic</td>
<td>Indicates valid transformed samples are being output from the core.</td>
</tr>
</tbody>
</table>

\(^1\) Both a synchronous and asynchronous reset are provided for portability. Only one of the reset circuits should be used depending on the target platform. The unused port should be tied to a logical constant (‘1’ for RESET_N, ‘0’ for CLEAR).
Timing Diagram
An overall sample timing diagram for a 1,024-point FFT is shown in Figure 2. In this example, 3 frames of input data are input into the core on the DATA_I and DATA_Q ports as the core becomes available as indicated by READY. As noted previously, the two reset circuits are mutually exclusive, thus in this example the RESET_N signal is tied to logic ‘1’ and the CLEAR signal is pulsed high at the start of the test.

The START signal is pulsed high for a single clock cycle at the start of each frame of input data, coincident with the first sample. The next \( N - 1 \) consecutive input samples following a START pulse are considered part of the same frame. Figure 3 shows a magnified view of the start of frame #2 and also shows a MODE change coincident with the START pulse for frame #2 to perform a forward FFT.

After the transform calculation latency, data is output on the FFT_DATA_I and FFT_DATA_Q ports and is indicated to be valid by the VALID port. Figure 2 shows each frame of data being input, processed, then output before the next frame is loaded. The READY port goes high as soon as output data is completely unloaded from the core, indicating that the core is ready to accept a new frame of input data. Figure 4 shows a magnified view of the start of output frame #1. In the example given in Figure 2, all 3 output frames have a block exponent of 7. Figure 4 shows a magnified view of the start of output frame #1.

The latency from the rising edge of the first START pulse to the first rising edge of VALID are provided in Table 4 for all supported transform lengths. The natural ordering latency and bit-reversed latency are the same for a given transform length due to buffer reuse in the serial architecture.

<table>
<thead>
<tr>
<th>Transform Length</th>
<th>Latency (clock cycles)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Natural Order</td>
</tr>
<tr>
<td>64</td>
<td>202</td>
</tr>
<tr>
<td>256</td>
<td>824</td>
</tr>
<tr>
<td>1,024</td>
<td>3,654</td>
</tr>
<tr>
<td>4,096</td>
<td>16,468</td>
</tr>
<tr>
<td>16,384</td>
<td>73,826</td>
</tr>
<tr>
<td>65,536</td>
<td>327,792</td>
</tr>
</tbody>
</table>
Figure 2: Overall Timing Diagram

Figure 3: Start of Input Frame #2 Timing Diagram

Figure 4: Start of Output Frame #1 Timing Diagram
File List

Table 5 lists the VHDL source files included with the project. Source files are also included for both block floating-point and floating-point MATLAB models as listed in Table 6. Additionally, testbenches for VHDL and block floating-point and floating-point MATLAB models are included as listed in Table 7 and Table 8.

### Table 5: FFT/IFFT Core VHDL Source File List

<table>
<thead>
<tr>
<th>File Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>radix4_bfly.vhd</td>
<td>Radix-4 butterfly operations</td>
</tr>
<tr>
<td>radix4_dft.vhd</td>
<td>FFT signal processing top level</td>
</tr>
<tr>
<td>radix4_stage.vhd</td>
<td>Radix-4 stage processing and control</td>
</tr>
<tr>
<td>radix4_dft_pkg.vhd</td>
<td>Package file for useful types and functions</td>
</tr>
<tr>
<td>clamp_pkg.vhd</td>
<td>Package file for saturation functions</td>
</tr>
<tr>
<td>complex_multiplier_growth.vhd</td>
<td>Complex multiplier with data path growth support</td>
</tr>
<tr>
<td>dp_ram.vhd</td>
<td>Dual port RAM</td>
</tr>
<tr>
<td>math_pkg.vhd</td>
<td>Package file for math convenience functions</td>
</tr>
<tr>
<td>multiplier_s.vhd</td>
<td>Signed multiplier</td>
</tr>
<tr>
<td>shift_pkg.vhd</td>
<td>Package file for bit shifting functions</td>
</tr>
<tr>
<td>types_pkg.vhd</td>
<td>Package file for commonly used user-defined types</td>
</tr>
</tbody>
</table>

### Table 6: FFT/IFFT Core MATLAB Model Source File List

<table>
<thead>
<tr>
<th>File Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>radix4_bfly.m</td>
<td>Radix-4 butterfly operations</td>
</tr>
<tr>
<td>radix4_dft.m</td>
<td>FFT signal processing top level</td>
</tr>
<tr>
<td>radix4_stage.m</td>
<td>Radix-4 stage processing and control</td>
</tr>
<tr>
<td>clamp.m</td>
<td>Saturates input data</td>
</tr>
<tr>
<td>shift_down.m</td>
<td>Performs bit shifting operations on input data</td>
</tr>
</tbody>
</table>

### Table 7: FFT/IFFT Core VHDL Testbench File List

<table>
<thead>
<tr>
<th>File Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>radix4_dft_tb.vhd</td>
<td>Testbench associated with top level VHDL source</td>
</tr>
<tr>
<td>run_do</td>
<td>Modelsim-compatible script to compile source and testbench</td>
</tr>
<tr>
<td>testbench_pkg.vhd</td>
<td>Package file for testbench convenience functions</td>
</tr>
<tr>
<td>textio_pkg.vhd</td>
<td>Package file for text input/output; overloads/extends std.textio</td>
</tr>
</tbody>
</table>

### Table 8: FFT/IFFT Core MATLAB Testbench File List

<table>
<thead>
<tr>
<th>File Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>radix4_dft_tb.m</td>
<td>Testbench associated with top level MATLAB model</td>
</tr>
</tbody>
</table>
Functional Description
The Discrete Fourier Transform, of length $N$, takes $N$ complex time domain samples and expresses them in the frequency domain. The equation for the forward DFT is given as:

$$X[k] = \sum_{n=0}^{N-1} x_n \cdot e^{-j2\pi kn/N}$$

The inverse DFT reverses this process, transforming frequency domain signals into the time domain. The equation for the inverse DFT is given as:

$$x_n = \frac{1}{N} \sum_{k=0}^{N-1} X_k \cdot e^{j2\pi kn/N}$$

The implementation of this core uses a modified Sande-Tukey decimation-in-frequency (DIF) algorithm to reduce computational time and complexity over a brute force DFT implementation. The core supports power-of-four transform lengths formed from radix-4 stages up to 65,536 points. A block diagram of the radix-4 stage architecture is shown in Figure 5.
The inverse operation is supported by swapping the real and imaginary components of the input samples, performing the forward FFT, then swapping the real and imaginary components of the output samples. Note that this core differs slightly from the classical IFFT definition in that it does not perform the $\frac{1}{N}$ scaling as part of the internal implementation. The reordering buffers shown in Figure 5 can also be optionally used to reorder the bit-reversed output samples to natural order during the output cycle.

For illustrative purposes, assume $N = 1,024$. Referring to Figure 5, the stage control logic block would serially iterate through the radix-4 stage 5 times to perform the 1,024 length transform. Once the 5 stage operations are complete, the output data is read out of the right reordering buffering.

The key to the FFT processing in this architecture is the radix-4 butterfly engine as shown in Figure 5. This implementation uses 2 single output radix-4 engines to balance minimizing processing latency and minimizing resource utilization. Data from the previous calculation cycle is reordered via reordering buffers (dual-port RAMs) and processed through a radix-4 butterfly. Scaled data is then processed by
the two single output radix-4 butterfly engines. The bit width of the data path through the single output radix-4 butterfly engine and the reordering buffers grows by up to 3 bits (i.e., a total bit width of \(g\text{DATA\_WIDTH} + 3\)) to prevent overflow for the current stage. Twiddle factors are applied via a complex multiplier. The processed data is written into another set of reordering buffers. The reordering buffers are accessed in a ping-pong buffer fashion, i.e. for stage iteration 0, the left reordering buffer is read and the right reordering buffer is written, for stage iteration 1, the left reordering buffer is written and the right reordering buffer is read, and so on.

**Resource Utilization**

To generate resource utilization estimates, build synthesis and implementation was performed using generic inputs shown in Table 9, producing a 1,024-point FFT/IFFT with 16-bit I/Q data.

<table>
<thead>
<tr>
<th>Generic</th>
<th>Type</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>gNUM_STAGES</td>
<td>natural</td>
<td>5</td>
</tr>
<tr>
<td>gDATA_WIDTH</td>
<td>natural</td>
<td>16</td>
</tr>
<tr>
<td>gTWIDDLE_WIDTH</td>
<td>natural</td>
<td>16</td>
</tr>
<tr>
<td>gORDERING</td>
<td>std_logic</td>
<td>'1'</td>
</tr>
<tr>
<td>gNUM_MULT_STAGES</td>
<td>natural</td>
<td>3</td>
</tr>
</tbody>
</table>

Resource estimates for several candidate Xilinx devices are shown in Table 10. Resource estimates for several candidate Altera devices are shown in Table 11. The asynchronous reset circuit for all Altera estimates and the synchronous reset circuit was used for all Xilinx estimates. For Xilinx devices, Vivado 2014.1 was used to generate resource estimates. For Altera devices, Quartus II 11.1 SP2 was used in estimate generation. Both vendors include several synthesis and implementation options that will impact resource utilization and maximum achievable circuit frequency (Fmax). The estimates reported in this document use the default values provided by each vendor for all synthesis and implementation options. The user can adjust vendor-specific settings to impact the performance/resource utilization tradeoff for their application. Contact GIRD Systems for assistance in tuning build parameters and constraints for specific application needs. Note that several other factors may cause variation in resource utilization and circuit performance estimates, such as overall device utilization, routing congestion, place-and-route/fitter seed, etc.
Table 10: Xilinx Device Utilization Estimates

<table>
<thead>
<tr>
<th>Device</th>
<th>Logic</th>
<th>Block RAMs</th>
<th>Multipliers</th>
<th>Fmax</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Slice</td>
<td>Block RAMs</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>LUTs</td>
<td>Registers</td>
<td>Multipliers</td>
<td></td>
</tr>
<tr>
<td>Artix 7</td>
<td>1,435</td>
<td>1,658</td>
<td>2</td>
<td>8</td>
</tr>
<tr>
<td>XC7A200T -1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Kintex 7</td>
<td>1,437</td>
<td>1,658</td>
<td>2</td>
<td>8</td>
</tr>
<tr>
<td>XC7K325T -1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Virtex 7</td>
<td>1,436</td>
<td>1,658</td>
<td>2</td>
<td>8</td>
</tr>
<tr>
<td>XC7VX485T -1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 11: Altera Device Utilization Estimates

<table>
<thead>
<tr>
<th>Device</th>
<th>Logic</th>
<th>Block RAMs</th>
<th>Multipliers</th>
<th>Fmax</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>LEs/ALUTs</td>
<td>Registers</td>
<td>M9Ks</td>
<td>M144Ks</td>
</tr>
<tr>
<td>Cyclone III</td>
<td>2,474</td>
<td>1,709</td>
<td>21</td>
<td>-</td>
</tr>
<tr>
<td>EP3C40 C8</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Cyclone IV</td>
<td>2,474</td>
<td>1,709</td>
<td>21</td>
<td>-</td>
</tr>
<tr>
<td>EP4CGX30 C8</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Stratix IV</td>
<td>2,010</td>
<td>1,523</td>
<td>19</td>
<td>0</td>
</tr>
<tr>
<td>EP4SE230 C4</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Stratix V</td>
<td>1,936</td>
<td>1,635</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>5SGSED6K C4</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Simulation

Most VHDL simulators should be capable of simulating the FFT/IFFT IP core. During development and testing of the core, ModelSim DE 10.1d and MATLAB 2009a were used for simulation. No additional external libraries or toolboxes are required. There are 3 provided testbenches: a block floating-point VHDL testbench, a bit-accurate block floating-point MATLAB testbench, and a floating-point MATLAB testbench. The VHDL testbench depends on stimulus data generated by the MATLAB block floating-point testbench. Thus, the MATLAB block floating-point testbench must be run prior to running the VHDL testbench.

For the block floating-point MATLAB testbench, several simulation and core parameters must be set to configure the test. The ‘gen_vectors’ flag configures if new stimulus data should be generated or existing data should be used. The ‘num_frames’ variable defines the number of frames to process in the current test. Note that if ‘num_frames’ is modified, new stimulus data should be generated so that the correct number of input samples are available. Each entry in the ‘modes’ vector defines the forward/reverse operation for each frame. The length of the ‘modes’ vector should be equal to
‘num_frames’. The core-specific parameters, like transform length, data width, schedule, etc., are defined in the ‘params’ structure.

In the VHDL testbench, there are several simulation and core configuration parameters that have corresponding parameters in the MATLAB block floating-point testbench. To achieve a bit-true comparison with the MATLAB model, these parameters must have the same values as the corresponding MATLAB testbench parameters. Table 12 lists the relevant MATLAB and corresponding VHDL simulation parameters. A ModelSim-compatible DO script is also included to compile the VHDL source and testbench.

Table 12 : Simulation Parameters

<table>
<thead>
<tr>
<th>MATLAB Parameter</th>
<th>VHDL Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>num_frames</td>
<td>cFRAMES</td>
<td>Number of frames to test</td>
</tr>
<tr>
<td>params.data_width</td>
<td>cDATA_WIDTH</td>
<td>Bit width of the data samples</td>
</tr>
<tr>
<td>params.twiddle_width</td>
<td>cTWIDDLE_WIDTH</td>
<td>Bit width of twiddle factors</td>
</tr>
<tr>
<td>params.num_stages</td>
<td>cNUM_STAGES</td>
<td>Number of transform stages</td>
</tr>
<tr>
<td>modes</td>
<td>cMODE</td>
<td>Forward or inverse operation</td>
</tr>
<tr>
<td>params.ordering</td>
<td>cORDERING</td>
<td>Bit-reversed or natural output ordering</td>
</tr>
</tbody>
</table>